

GEORGIA INSTITUTE OF TECHNOLOGY  
SCHOOL of ELECTRICAL and COMPUTER ENGINEERING

EE 2200 Spring 1999  
Problem Set #6

Assigned: 14 May 99  
Due Date: 21 May 99 (FRIDAY)

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**Quiz #2 will be held on 24-May-99. Closed book, calculators permitted, and one page of hand-written formulas** ( $8\frac{1}{2}'' \times 11''$ ). It will cover material from Chapters 3, 4, 5, and 6, as represented in Problem Sets #4, #5 and #6.

Reading: In *DSP First*, Chapter 6 on *Frequency Response* and Chapter 7 on *z-Transforms*.

The last lab quiz is planned for the labs on 20-May.

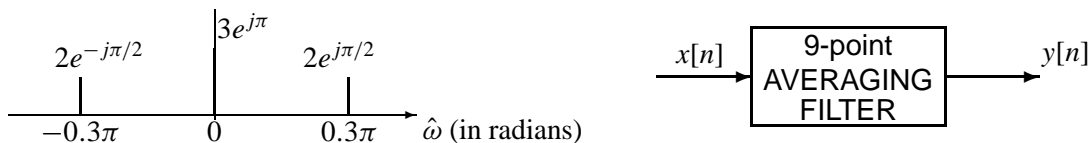
⇒ The six **STARRED** problems will have to be turned in for grading.

Next week a solution will be posted. Some similar problems solutions can be found on the CD-ROM, especially the “unstarred” problems.

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**PROBLEM 6.1\*:**

A discrete-time signal  $x[n]$  has the two-sided spectrum representation shown below.



- Write an equation for  $x[n]$ . Make sure to express  $x[n]$  as a real-valued signal.
- Use the MATLAB GUI called `ltdemo.m` to determine the output  $y[n]$  when the FIR filter is a 9-point averaging filter. Include a screen shot of the result from `ltdemo`.
- Determine the formula for the output signal  $y[n]$ . Do this calculation by hand.

**PROBLEM 6.2\*:**

For the *Dirichlet* function:

$$D(\hat{\omega}, 9) = \frac{\sin(4.5\hat{\omega})}{\sin(\frac{1}{2}\hat{\omega})}$$

- Make a plot of  $D(\hat{\omega}, 9)$  over the range  $-2\pi \leq \hat{\omega} \leq +2\pi$ . Label all the zero crossings.
- Determine the period of  $D(\hat{\omega}, 9)$ . Is it equal to  $2\pi$ ; why, or why not?
- Find the maximum value of the function.

NOTE: the *Dirichlet* function is defined via:  $D(\hat{\omega}, L) = \frac{\sin(L\hat{\omega}/2)}{\sin(\frac{1}{2}\hat{\omega})}$

In MATLAB consult help on `diric` for more information.

**PROBLEM 6.3\*:**

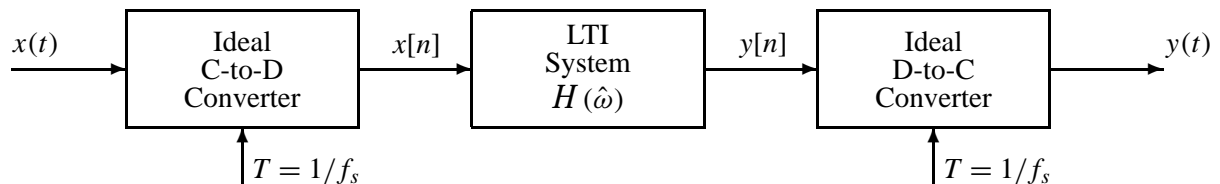
The input to the C-to-D converter in the figure below is

$$x(t) = 3 + 4 \cos(3000\pi t + \pi/2) + 12 \cos(20000\pi t - 2\pi/3)$$

The frequency response for the digital filter (LTI system) is

$$H(\hat{\omega}) = \frac{\sin(4.5\hat{\omega})}{\sin(\frac{1}{2}\hat{\omega})} e^{-j4\hat{\omega}}$$

If  $f_s = 10000$  samples/second, determine an expression for  $y(t)$ , the output of the D-to-C converter.

**PROBLEM 6.4\*:**

The intention of the following MATLAB program is to filter a sinusoid via the `conv` function, but the cosine signal has a starting point at  $n = 0$ ; we assume that it is zero for  $n < 0$ .

```
omega = pi/2;
nn = [ 0:4000 ];
xn = cos(omega*nn - pi/2);
bb = [ 1 0 0 0 1 ];
yn = conv( bb, xn );
```

- Determine  $H(\hat{\omega})$  for the FIR filter.
- Make a plot of the magnitude of  $H(\hat{\omega})$  and label *all* the frequencies where  $|H(\hat{\omega})|$  is zero.
- Determine a formula for  $y[n]$ , the signal contained in the vector `yn`. Give the individual values for  $n = 0, 1, 2, 3$ , and then provide a general formula for  $y[n]$  that is correct for  $4 \leq n \leq 4000$ . This formula should give numerical values for the amplitude, phase and frequency of  $y[n]$ .
- Give at least one value of  $\omega$  such that the output is guaranteed to be zero, for  $n \geq 4$ .

**PROBLEM 6.5\*:**

Suppose that three systems are hooked together in “cascade.” In other words, the output of  $\mathcal{S}_1$  is the input to  $\mathcal{S}_2$ , and the output of  $\mathcal{S}_2$  is the input to  $\mathcal{S}_3$ . The three systems are specified as follows:

$$\mathcal{S}_1 : \quad y_1[n] = 3x_1[n] - 3x_1[n - 1]$$

$$\mathcal{S}_2 : \quad y_2[n] = 2x_2[n] + 2x_2[n - 2]$$

$$\mathcal{S}_3 : \quad H_3(\hat{\omega}) = e^{-j\hat{\omega}} + e^{-j2\hat{\omega}}$$

NOTE: the output of  $\mathcal{S}_i$  is  $y_i[n]$  and the input is  $x_i[n]$ .

The objective in this problem is to determine the equivalent system that is a single operation from the input  $x[n]$  (into  $\mathcal{S}_1$ ) to the output  $y[n]$  which is the output of  $\mathcal{S}_3$ . Thus  $x[n]$  is  $x_1[n]$  and  $y[n]$  is  $y_3[n]$ .

- Determine the frequency response  $H_i(\hat{\omega})$  for  $i = 1, 2$ .
- Determine the difference equation for  $\mathcal{S}_3$ .
- Determine the  $z$ -transform system function  $H_i(z)$  for each system.
- Write *one difference equation* that defines the overall system in terms of  $x[n]$  and  $y[n]$  only.

**PROBLEM 6.6\*:**

Suppose that a LTI system has system function equal to

$$H(z) = 1 + z^{-4}$$

- Determine the difference equation that relates the output  $y[n]$  of the system to the input  $x[n]$ .
- Determine all the zeros of the  $z$ -transform system function,  $H(z)$ . In other words, solve  $H(z) = 0$ . Express your answer(s) in polar form.
- Suppose that the input signal is:

$$x[n] = \delta[n - 1] + 2\delta[n - 3] + 3\delta[n - 5]$$

Determine the output  $y[n]$  by using *convolution*.

- Demonstrate how the output of the system can also be obtained by multiplying  $H(z)$  times the polynomial:

$$X(z) = z^{-1} + 2z^{-3} + 3z^{-5}$$

Describe how the polynomial coefficients of  $X(z)$  and  $Y(z) = H(z)X(z)$  are related to  $x[n]$  and  $y[n]$ , respectively.