

## ***Robust Constrained Optimization***

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Lecture 23

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## **Where We Are in J&D**

- **Section 7.4.3**
- **Note: these slides will use  $\mathbf{R}$  instead of  $\mathbf{R}_y$**

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## **Adaptive Techniques So Far**

- **Recall MVDR formulation:**  
$$\min_{\mathbf{w}} \mathbf{w}^H \mathbf{R} \mathbf{w} \text{ s.t. } \mathbf{e}^H(\vec{k}) \mathbf{w} = 1$$
- **Then derived EV, MUSIC, etc.**

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## **Some Potential Problems**

- **Problem: If we don't know  $\mathbf{e}(\vec{k})$  exactly, these techniques may break down**
- **Sensitivity to model mismatches increases with SNR!**
- **Overall sensitive to quality of estimate of  $\mathbf{R}$**

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### Problems with Few Snapshots

- All methods use empirical correlation matrix:

$$\hat{\mathbf{R}} = \frac{1}{L} \sum_{l=0}^{L-1} \mathbf{y}(l) \mathbf{y}^H(l)$$

- All methods need a “full rank”  $\hat{\mathbf{R}}$
  - Hence, need  $L \geq M$
- No. of snapshots  $\nearrow$   $\nwarrow$  No. of sensors

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### Try Building Errors into Formulation

$$\min_{\mathbf{w}} \mathbf{w}^H \mathbf{R} \mathbf{w} \text{ s.t. } (\mathbf{e} + \boldsymbol{\delta})^H \mathbf{w} = 1$$

$$\text{and } \|\boldsymbol{\delta}\|^2 = \boldsymbol{\delta}^H \boldsymbol{\delta} \leq \varepsilon^2$$

- Note will also need to “find”  $\boldsymbol{\delta}$
- Use Lagrange multipliers

$$L = \mathbf{w}^H \mathbf{R} \mathbf{w}$$

$$+ \lambda_1^* [(\mathbf{e} + \boldsymbol{\delta})^H \mathbf{w} - 1] + \lambda_1 [(\mathbf{e} + \boldsymbol{\delta})^T \mathbf{w}^* - 1]$$

$$+ \lambda_2 [\boldsymbol{\delta}^H \boldsymbol{\delta} - \varepsilon^2]$$

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### Taking Gradients

$$L = \mathbf{w}^H \mathbf{R} \mathbf{w}$$

$$+ \lambda_1^* [(\mathbf{e} + \boldsymbol{\delta})^H \mathbf{w} - 1] + \lambda_1 [\mathbf{w}^H (\mathbf{e} + \boldsymbol{\delta}) - 1]$$

$$+ \lambda_2 [\boldsymbol{\delta}^H \boldsymbol{\delta} - \varepsilon^2]$$

$$\nabla_{\mathbf{w}^*} L = \mathbf{R} \mathbf{w} + \lambda_1 (\mathbf{e} + \boldsymbol{\delta}) = 0$$

$$\nabla_{\boldsymbol{\delta}^*} L = \lambda_1^* \mathbf{w} + \lambda_2 \boldsymbol{\delta} = 0$$

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### Constraint on Errors is Operative

$$\lambda_1^* \mathbf{w} + \lambda_2 \boldsymbol{\delta} = 0$$

- From Appendix C, either  $\lambda_2 = 0$  or  $\|\boldsymbol{\delta}\|^2 = \varepsilon^2$
- Taking  $\lambda_2 = 0 \rightarrow \mathbf{w} = 0$
- So instead take  $\lambda_2 \neq 0$

$$\rightarrow \boldsymbol{\delta} = -\frac{\lambda_1^*}{\lambda_2} \mathbf{w}$$

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### Eliminating the Explicit Errors

$$\delta = -\frac{\lambda_1^*}{\lambda_2} \mathbf{w}$$

↓

$$\mathbf{R}\mathbf{w} = -\lambda_1(\mathbf{e} + \delta)$$
$$\mathbf{R}\mathbf{w} = -\lambda_1\left(\mathbf{e} - \frac{\lambda_1^*}{\lambda_2} \mathbf{w}\right)$$
$$\mathbf{R}\mathbf{w} = -\lambda_1\mathbf{e} + \frac{|\lambda_1|^2}{\lambda_2} \mathbf{w}$$

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### Boring Manipulations

$$\mathbf{R}\mathbf{w} = -\lambda_1\mathbf{e} + \frac{|\lambda_1|^2}{\lambda_2} \mathbf{w}$$
$$\left(\mathbf{R} - \frac{|\lambda_1|^2}{\lambda_2} \mathbf{I}\right) \mathbf{w} = -\lambda_1\mathbf{e}$$
$$\mathbf{w} = -\lambda_1 \left(\mathbf{R} - \frac{|\lambda_1|^2}{\lambda_2} \mathbf{I}\right)^{-1} \mathbf{e}$$

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### Yes, the Inverse is Well Defined

$$\mathbf{w}_\diamond = -\lambda_1 \left(\mathbf{R} - \frac{|\lambda_1|^2}{\lambda_2} \mathbf{I}\right)^{-1} \mathbf{e}(\vec{k})$$

- Can show  $\lambda_1 < 0$ ,  $\lambda_2 < 0$ , so

$$\mathbf{R} - \frac{|\lambda_1|^2}{\lambda_2} \mathbf{I} \text{ is invertible}$$

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### Running into Trouble

$$\mathbf{w}_\diamond = -\lambda_1 \left(\mathbf{R} - \frac{|\lambda_1|^2}{\lambda_2} \mathbf{I}\right)^{-1} \mathbf{e}(\vec{k})$$

- Computing  $\lambda_1, \lambda_2$  is difficult
- Several possible solutions for  $\lambda_1, \lambda_2$ ; must check which minimizes  $\mathbf{w}^H \mathbf{R} \mathbf{w}$
- $\lambda_1, \lambda_2$  change with  $\vec{k}$

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### Punting

$$\mathbf{w}_\diamond = -\lambda_1 \left( \mathbf{R} - \frac{|\lambda_1|^2}{\lambda_2} \mathbf{I} \right)^{-1} \mathbf{e}(\vec{k})$$

- Let's try something ad-hoc:  
$$\mathbf{w}_\diamond = (\mathbf{R} + \alpha \mathbf{I})^{-1} \mathbf{e}(\vec{k}), \alpha > 0$$
- “diagonal loading,” “ridge regression,” “Tikhonov regularization”

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### Interpretation of Added Term

$$\mathbf{w}_\diamond = (\mathbf{R} + \alpha \mathbf{I})^{-1} \mathbf{e}(\vec{k}), \alpha > 0$$

- Adding additional “white noise” to  $\mathbf{R}$  used in computing weights
- Remember sensitivity to errors increases with SNR
- Artificially decrease apparent SNR to decrease sensitivity

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### Alternative Problem Formulation

$$\min_{\mathbf{w}} \mathbf{w}^H \mathbf{R} \mathbf{w} \text{ s.t. } \mathbf{e}^H \mathbf{w} = 1$$

and  $\|\mathbf{w}\|^2 = \mathbf{w}^H \mathbf{w} \leq \beta$

- Use Lagrange multipliers

$$L = \mathbf{w}^H \mathbf{R} \mathbf{w} + \lambda_1^* [\mathbf{e}^H \mathbf{w} - 1] + \lambda_1 [\mathbf{e}^T \mathbf{w}^* - 1] + \lambda_2 [\mathbf{w}^H \mathbf{w} - \beta]$$

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### Taking Gradients

$$L = \mathbf{w}^H \mathbf{R} \mathbf{w} + \lambda_1^* [\mathbf{e}^H \mathbf{w} - 1] + \lambda_1 [\mathbf{w}^H \mathbf{e} - 1] + \lambda_2 [\mathbf{w}^H \mathbf{w} - \beta]$$

$$\nabla_{\mathbf{w}^*} L = \mathbf{R} \mathbf{w} + \lambda_1 \mathbf{e} + \lambda_2 \mathbf{w} = 0$$

- If  $\lambda_2 = 0$ , get original MVDR (means  $\|\mathbf{w}\|^2 \leq \beta$  is inoperative)

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### Results for Alternate Formulation

- If  $\lambda_2 \neq 0$ , we have

$$\mathbf{R}\mathbf{w} + \lambda_1\mathbf{e} + \lambda_2\mathbf{w} = 0$$

$$(\mathbf{R} + \lambda_2\mathbf{I})\mathbf{w} = -\lambda_1\mathbf{e}$$

$$\mathbf{w} = -\lambda_1(\mathbf{R} + \lambda_2\mathbf{I})^{-1}\mathbf{e}$$

- Same sort of structure as before!

