

Transit Signal Priority: Help or Hype?

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Transit Signal Priority – Help or Hype?

- Zurich: nearly zero traffic delay and impeccable punctuality for trams
- Portland, San Diego: green wave for light rail station-to-station
- Yet, many US applications: < 2 s savings per intersection , or ...
- No measurement at all

Transit Priority as a Societal Objective

- Transit use benefits society in terms of
 - Congestion
 - Air quality, climate impact, energy use
 - Vibrant communities
- Priority breaks the vicious cycle in which congestion drives people to switch from transit to car

Priority Makes Sense

- One extreme (\$\$\$\$): build a metro
- Other extreme: do nothing, buses become swamped in congestion
 - Traffic delay can represent 30% of a bus route's operating cost
 - Feeds vicious cycle of ever-lower transit use
- In between:
 - Priority in space: bus lanes, etc.
 - Priority in time: signal priority

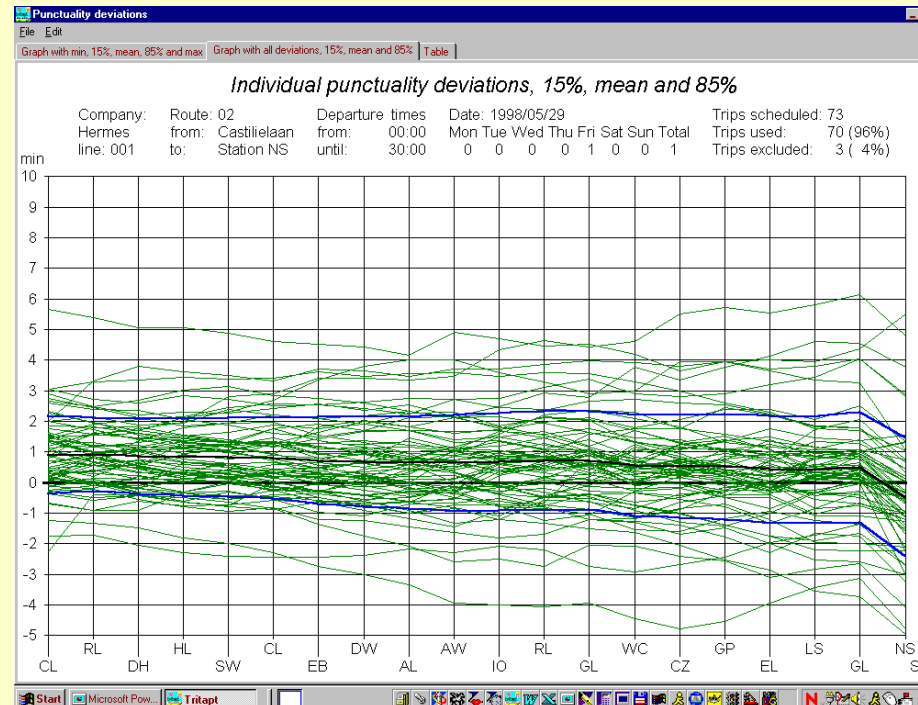
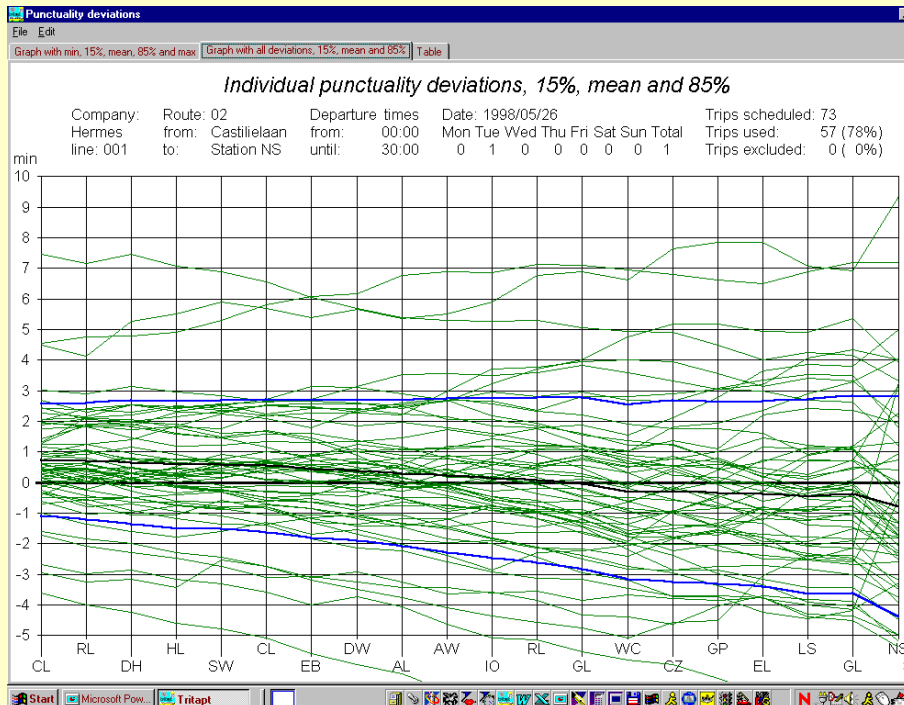
What Priority Means to a Transit Operation

- Reduced running time (\$\$, passenger benefit).
Measures:
 - Delay per intersection
 - Average route running time
- Improved reliability (\$\$, passenger benefit).
 - Recovery time, cycle time based on 95-percentile running time
 - Tri-Met Line 12: reduced needed cycle length from 104 min to 93 min (11%)

Operational Control: Schedule Adherence, Crowding

Schedule deviation along the route, without priority, Eindhoven

With priority



Priority Makes Transit ...

- More competitive
 - Bus has natural disadvantages due to *stops* and *walking / waiting*
 - Priority compensates, especially if cars suffer congestion
- More socially acceptable (red carpet)
 - my great aunt ...

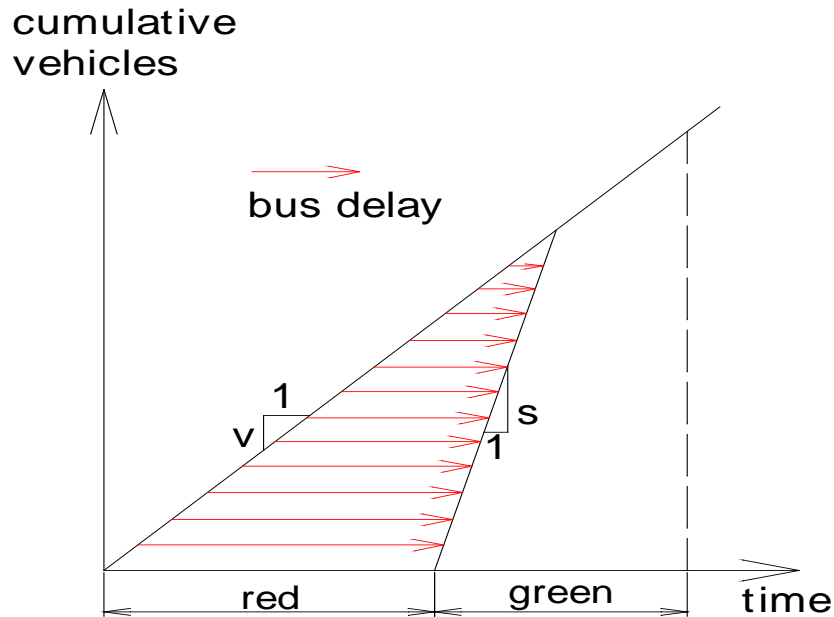
Levels of Priority in Modern Traffic Signal Controllers

- Highest level (**preemption**) reserved for emergency vehicles and railroad crossings
- Pre-programmed “priority” tactics include **green extension** and **early green**
- More intelligent tactics require custom programming, usually with central control & communication

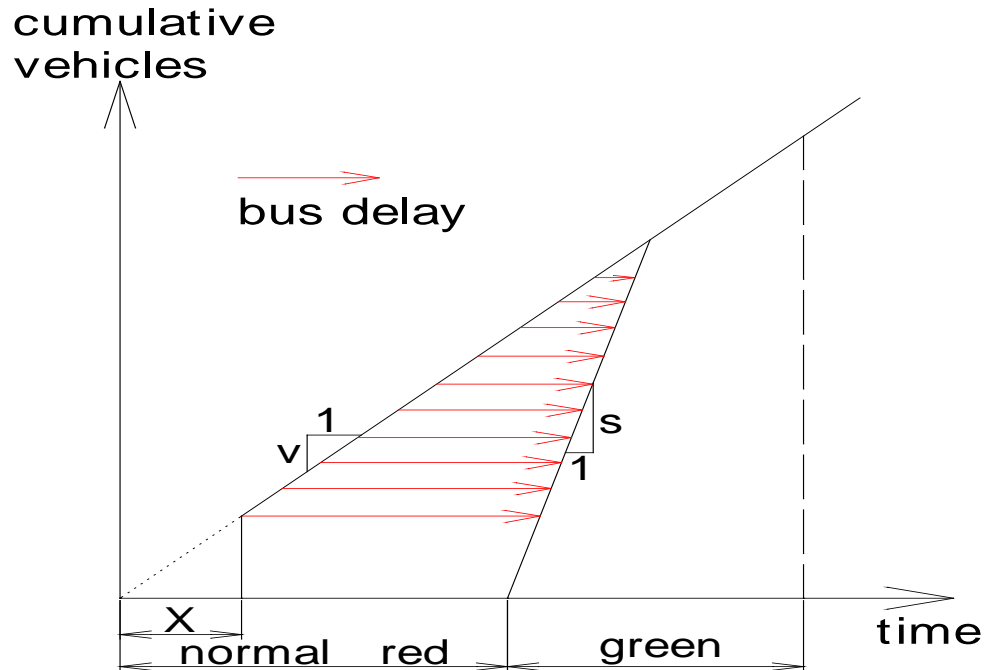
Green Extension

- Built-in logic in modern controllers
- **Large** benefit to a **few** buses
 - Therefore little disruption to traffic
- Extension increment is a parameter (10 s? 15 s?)

Without priority

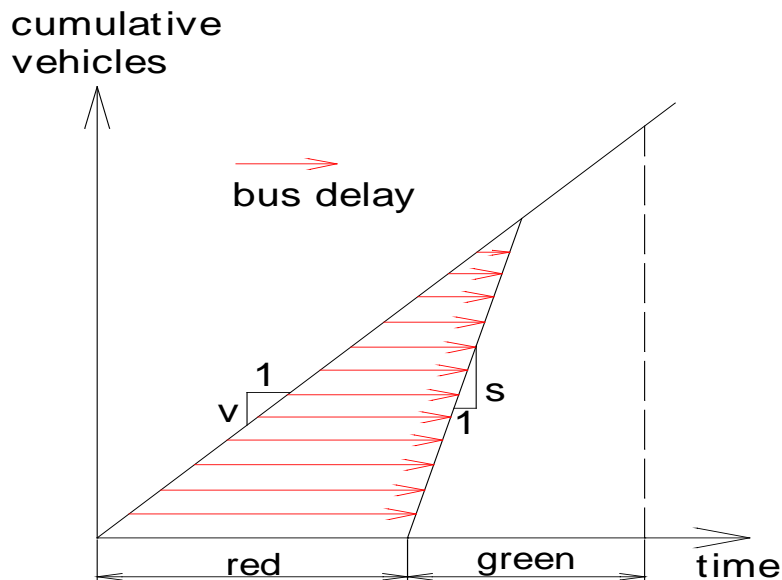


With green extension



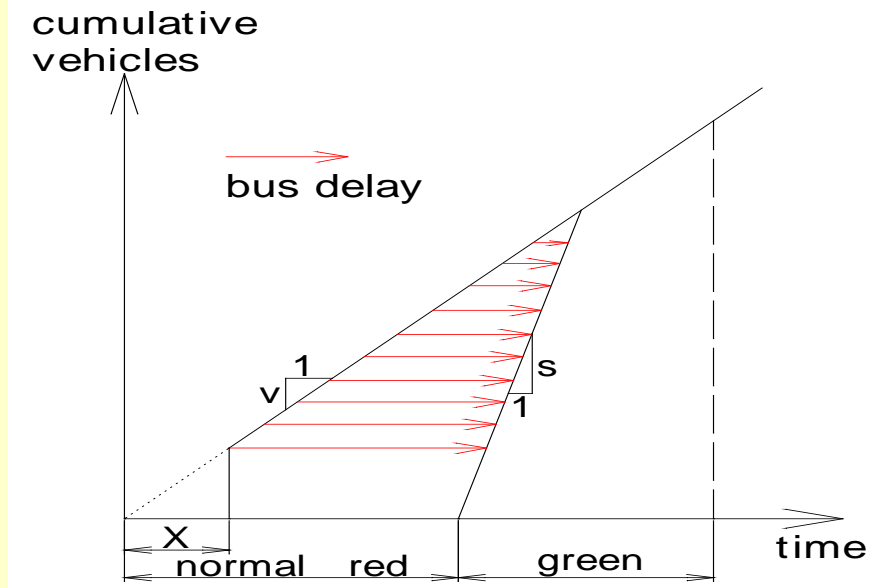
“Priority Push” is not the same as Allowed Extension

Without priority



$$E[\text{delay}] = \frac{R^2}{2C} \frac{1}{1-v/s}$$

With green extension

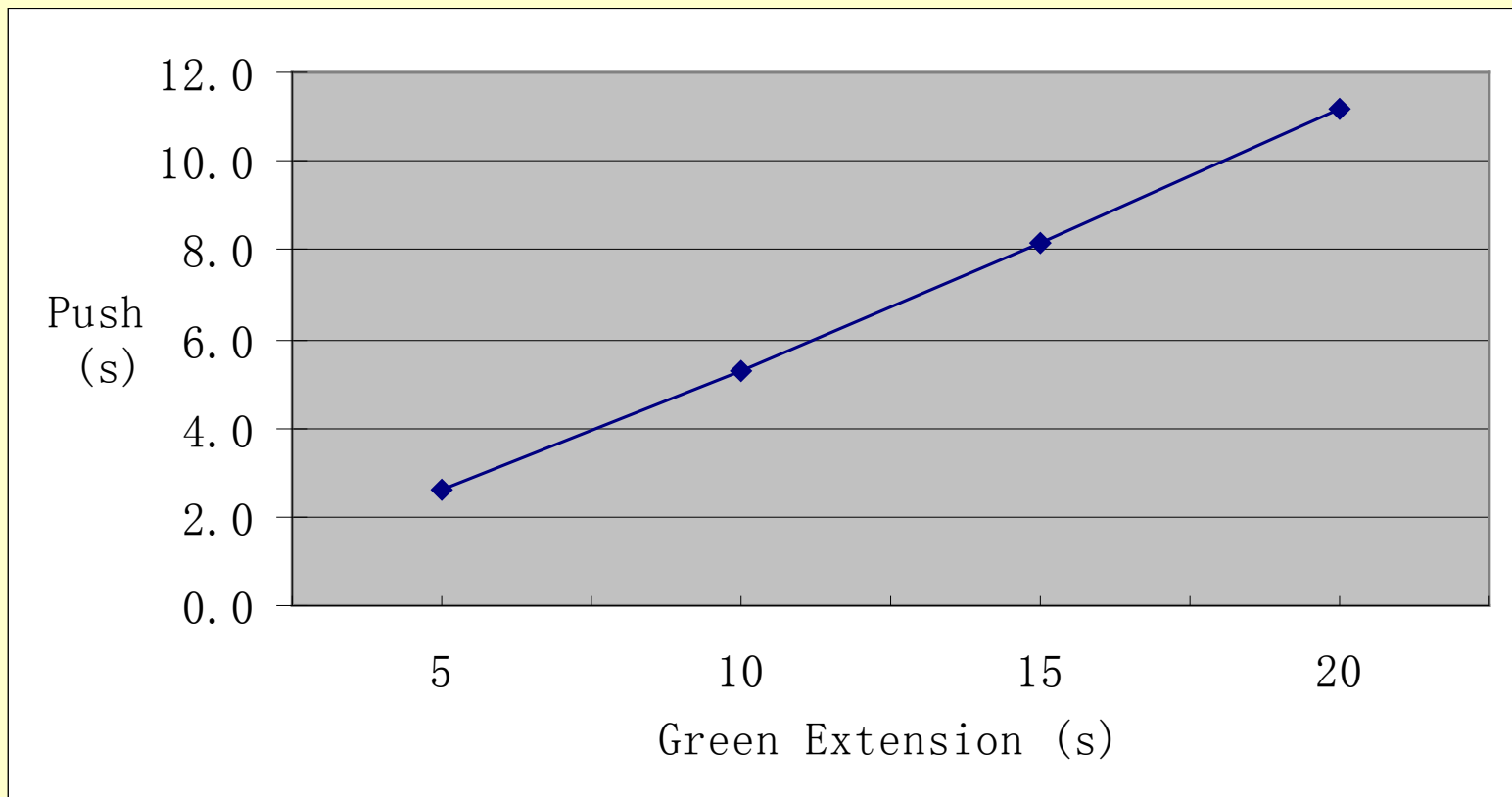


$$E[\text{delay}] = \frac{R^2}{2C} \frac{1}{1-v/s} - \left[X \frac{R}{C} - \frac{X^2}{2C} (1-v/s) \right]$$

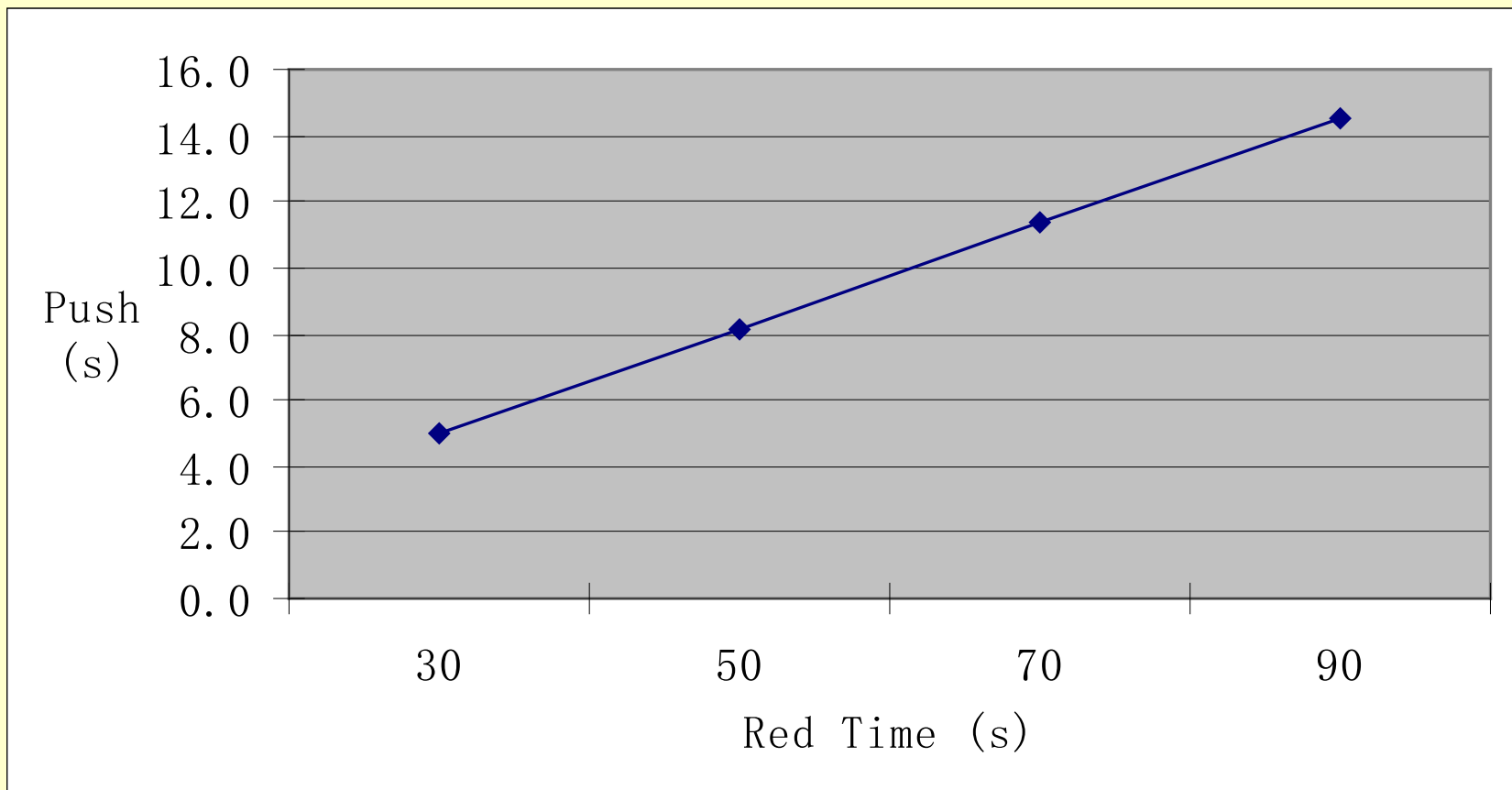
*Priority
push!*

Priority Push vs. Green Extension

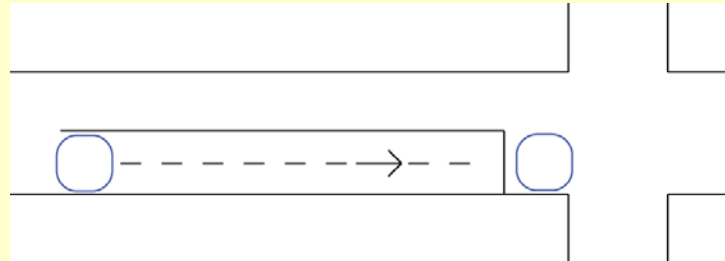
(cycle length = 100 s, red time = 50 s,
degree of saturation = 85%)



Priority Push vs. Red Time for allowed green extension of 15 s (cycle length = 100 s, degree of saturation = 85%)

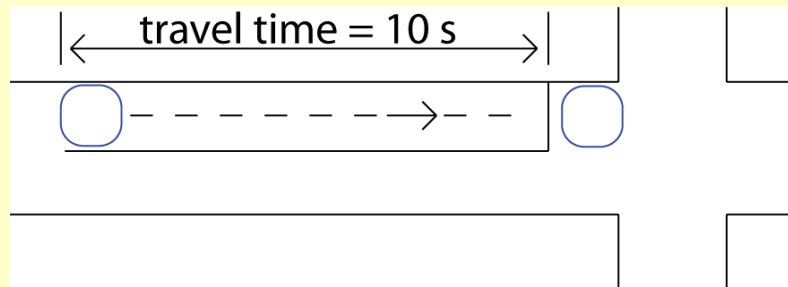


Detection



- Check-in detector location
 - Early enough to allow time to respond
 - Late enough to estimate bus arrival time
- Checkout detector to cancel request
 - Avoid wasted green
 - Performance measurement
- Fixed detector (buried antenna)
- AVL plus communication with the signal control box can serve as a detector

Upstream Detector for Green Extension: travel time = maximum green extension



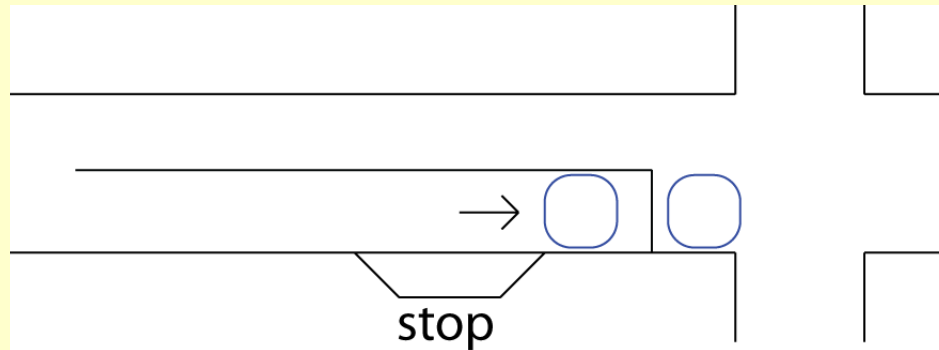
Simplicity:

- Request = detection

Weaknesses:

- assumes constant speed
- no flexibility for updates, time of day settings
- may not be suitable for other priority tactics

What if There's a Near-Side Stop?



- Detector located just after stop
- Disable optical signal until door closes (Portland, OR)
- Possible need for priority against a vehicle queue blocking entry to the bus stop

Common Weaknesses in Signal Priority Implementation

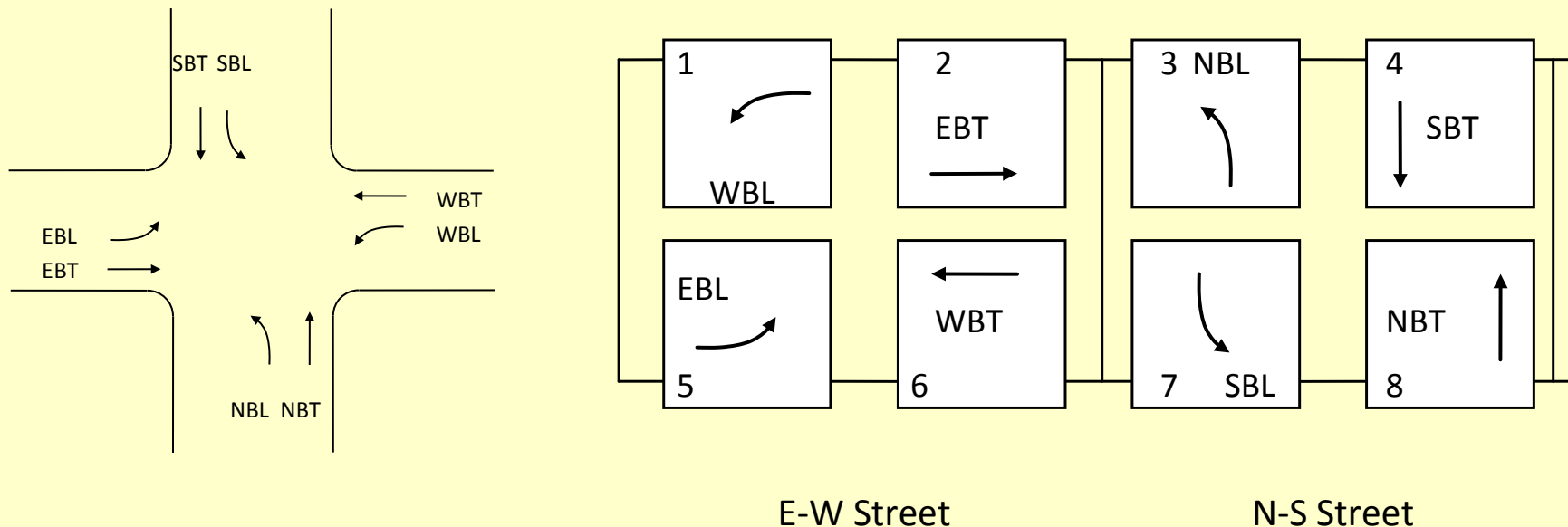
1. “Cautious priority:” Inhibit priority ...
 - for 5 minutes or 1 full cycle after priority interruption
 - if cross street occupancy exceeds threshold
2. Unnecessarily hurting traffic (leading to cautious priority)
 - Lack of checkout detector = wasted green
 - **Lack of compensation** creates large queuing impacts
 - Inflexibility in standard “coordination” logic
3. Apply easy, rather than intelligent, tactics
4. Lack of data collection and analysis
 - Nobody ever gets it right the first time
 - Taking the objective seriously

Fully actuated (uncoordinated) signal control naturally compensates

- Fully actuated = hold green until the queue clears (subject to min, max green)
- Interrupted phases get longer green in the next cycle, usually enough to clear the queue
- Transit phase
 - Priority green allows extra cars to be served
 - Reduces demand for green time in the next cycle
- System quickly recovers

Lack of compensation in coordinated systems

- Fixed cycle length
- Fixed point = end of coordinated phase
- Uncoordinated phases may run shorter than their allotted split, but not longer
- Coordinated phase gets the slack time (starts early)



Suppose coordinated phase is 2 (EBT)

- Green extension for 2 – no mechanism for compensation
- Green extension for 4 – slight compensation

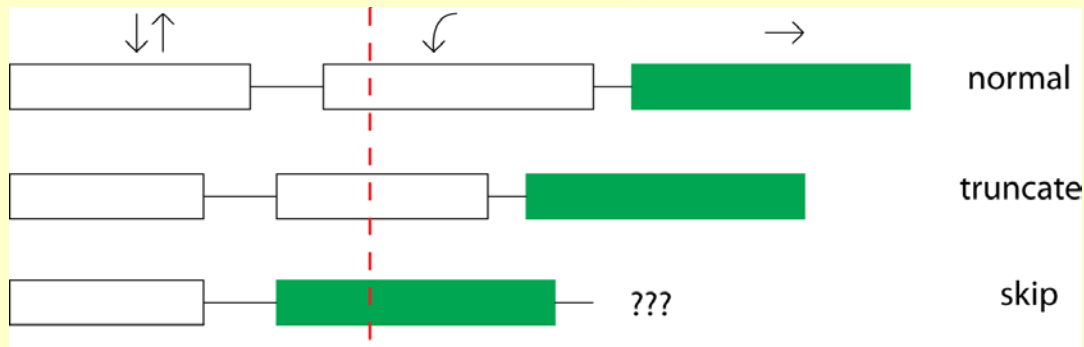
Returning to Coordination

In coordinated systems, recovery means

- dissipating queues AND
- Returning to the background cycle
 - “Short way” = shorten phases following an extension
 - “Long way” = lengthen phases, skip a cycle

Early Green

Truncate and possibly skip preceding phases

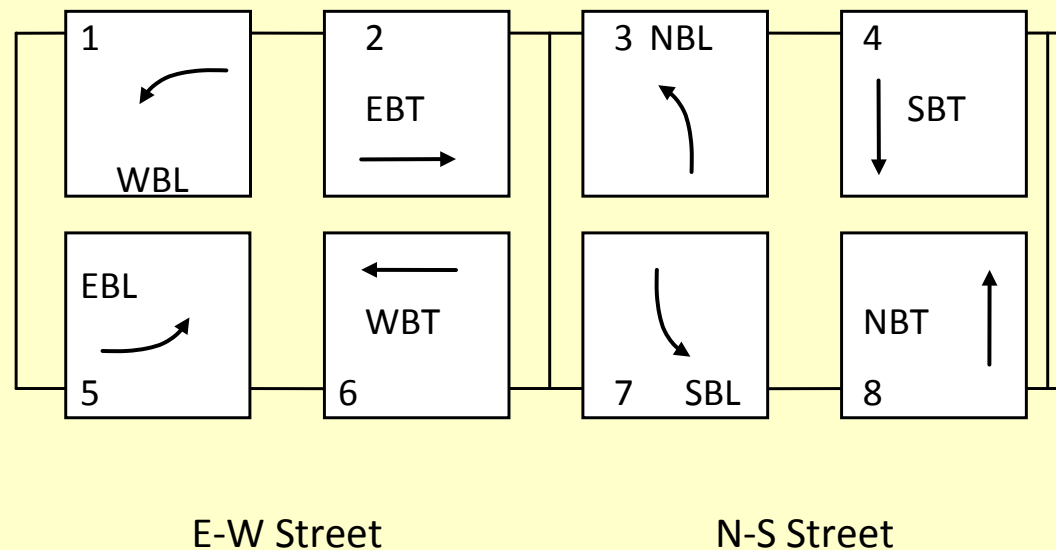


- What's the truncation rule?
 - How much to shorten competing phases? Can they be skipped?
- **Smaller** benefit to **large** number of buses
 - More traffic impact; hard to implement when bus frequency is high

Early Green Issues

- Exclusive lane for bus? (No queue, easier arrival time prediction)
- Mixed traffic: Eindhoven's "electronic bulldozer"
- Arrival time prediction
 - How far upstream? (Bus stop and intersection spacing ...)
 - Tracking queue length to know how long is needed to flush out the queue (Zurich's trap logic)

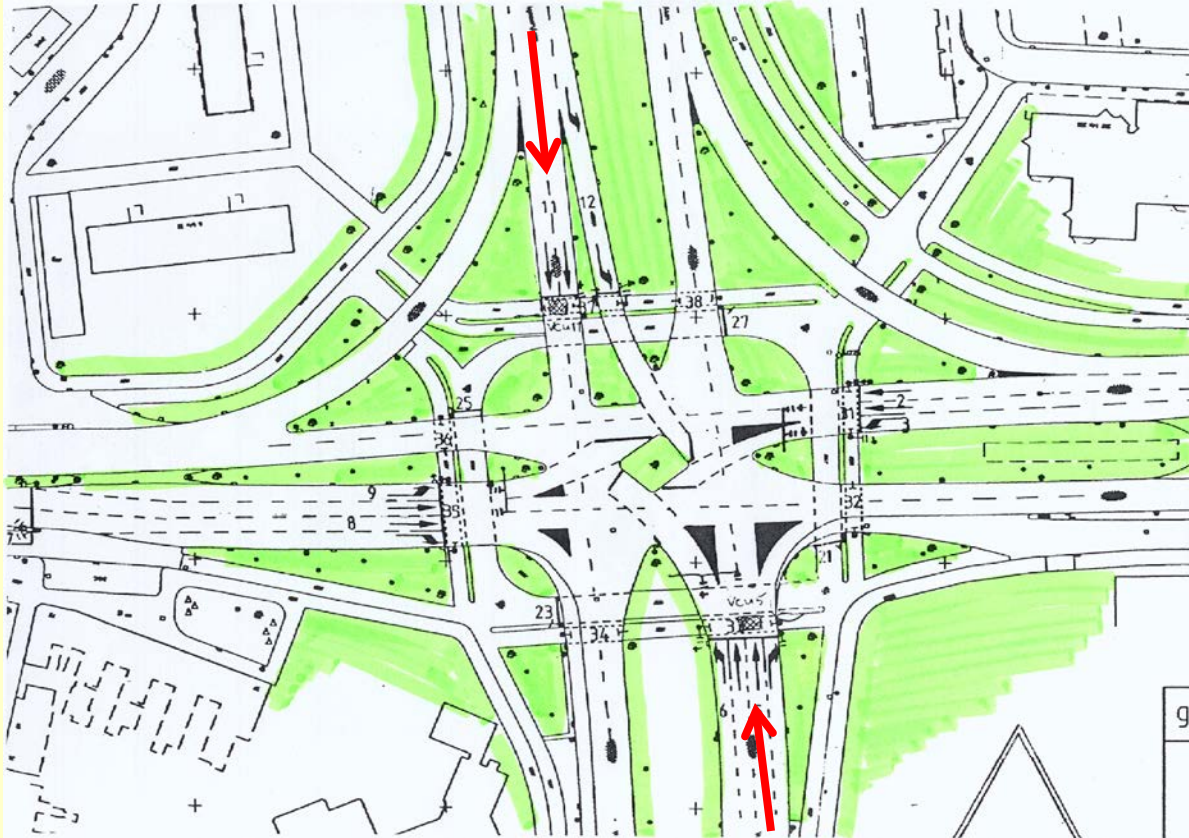
Early green (truncating competing phases) under coordination



Assume phase 2 is coordinated

- Early green for 2 is possible, but without compensation to shortened phases
- Early green for 3 – not possible under standard logic

Eindhoven Experiment



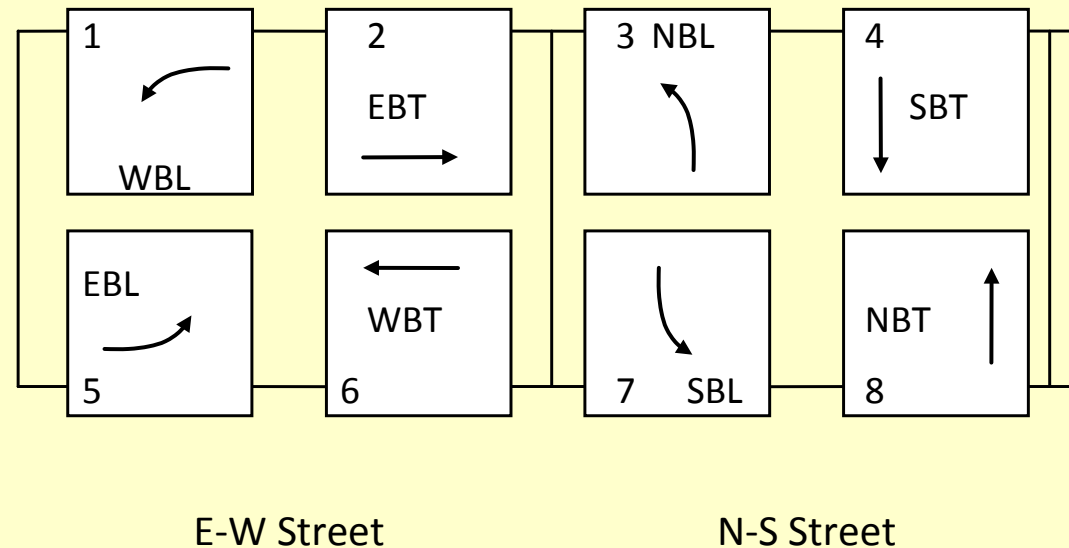
**Coordinated phase
(ring road, no buses)**



**Buses every 10
min NB and SB**

Existing Priority Scheme

- Coordinated phase is 6
- Buses are on 4 and 8 (every 10 minutes)
- Priority only if bus is more than 20 s late (about half the buses)

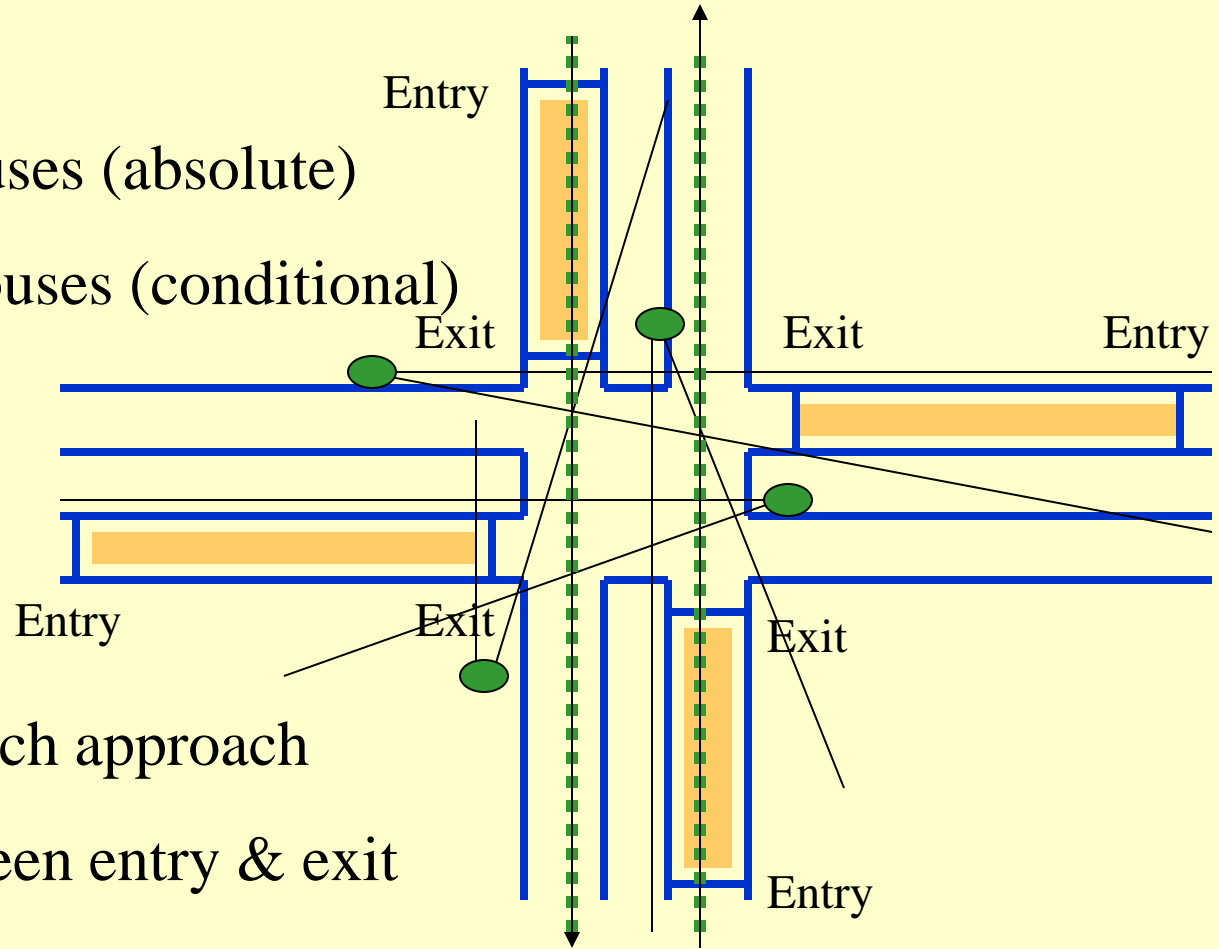


- Green extension
- Aggressive early green: reduce intervening phases to minimum green
- “Short way” minimum green to return to background cycle₂₄

Intersection Experiment and Site Description

One day each of

- priority to all buses (absolute)
- priority to late buses (conditional)
- no priority



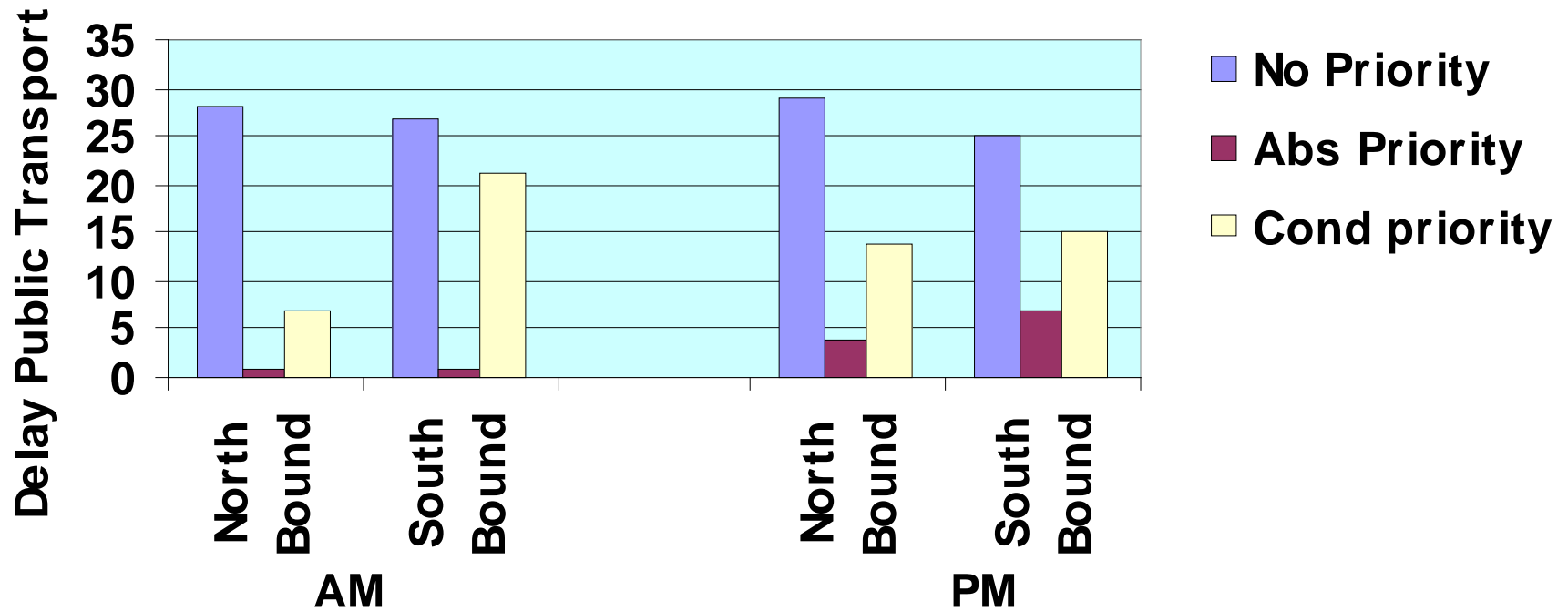
Camera facing each approach

Film “trap” between entry & exit

Playback in lab

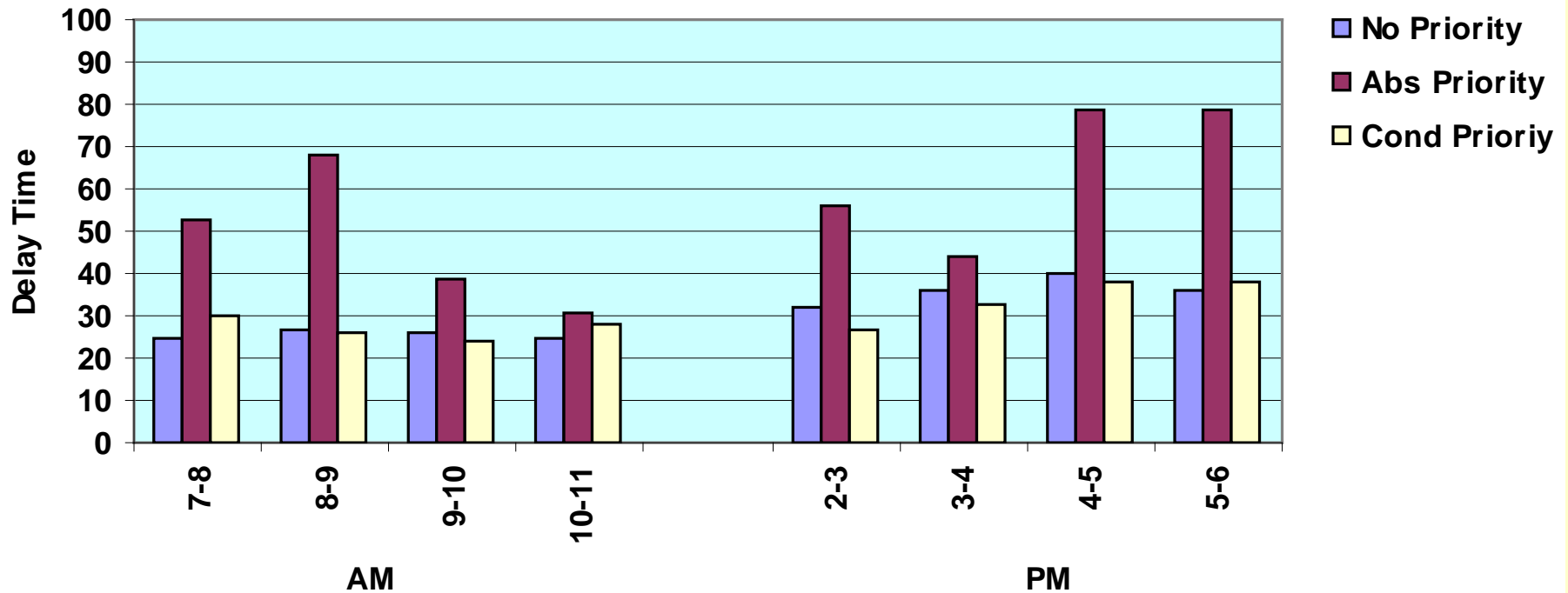
Experiment Eindhoven

Average Transit Delay [sec]



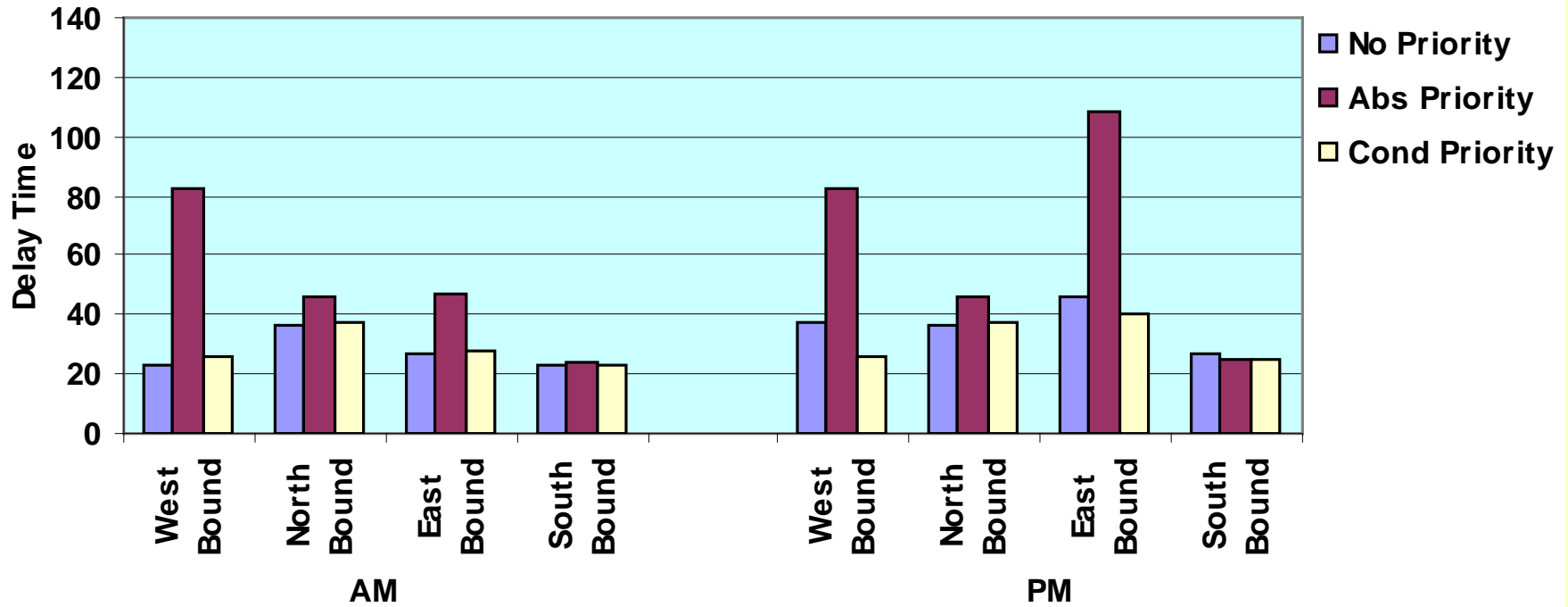
Experiment Eindhoven: Traffic Impact

Average Vehicle Delay [sec]



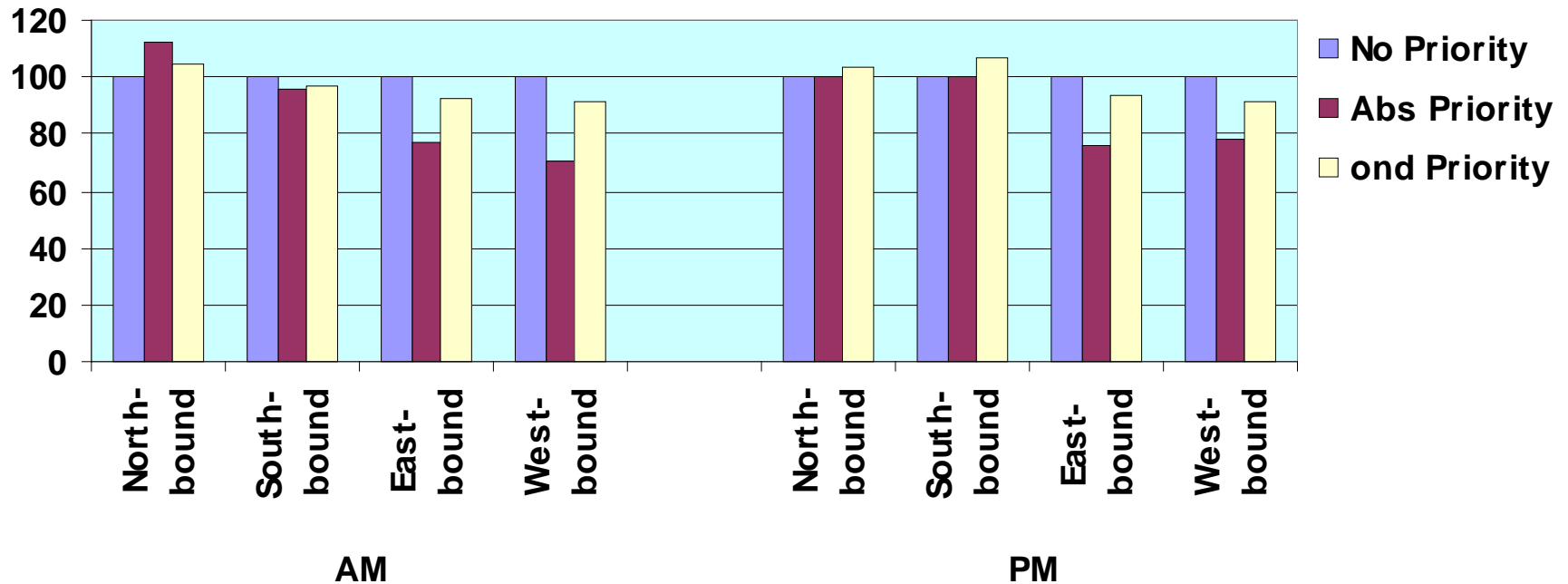
Experiment Eindhoven

Average Vehicle Delay per Approach [sec]



Experiment Eindhoven

Relative Capacity per Approach (no priority = 100%)

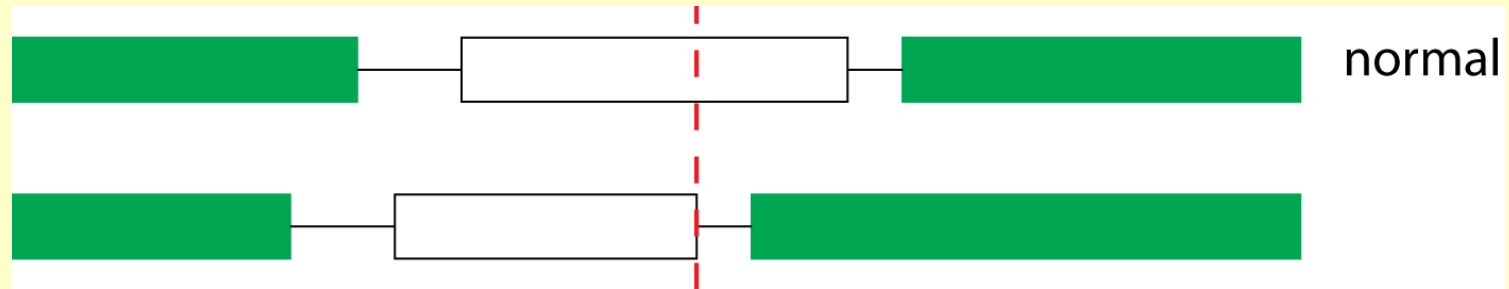


Lessons from Eindhoven

- Aggressive early green resulted in near-zero delay for buses
- Conditional priority needs finely-tuned schedule
 - Schedule too tight – bus always late – absolute priority
 - Schedule too loose – bus always early – no priority
- Lack of compensation: OK for 6 interruptions per hour, but not 12
- Capacity loss due to
 - Early green truncations, but more from ...
 - “short way” recovery to background cycle

Early Red

Shorten bus street's current green to get faster return to green in the next cycle

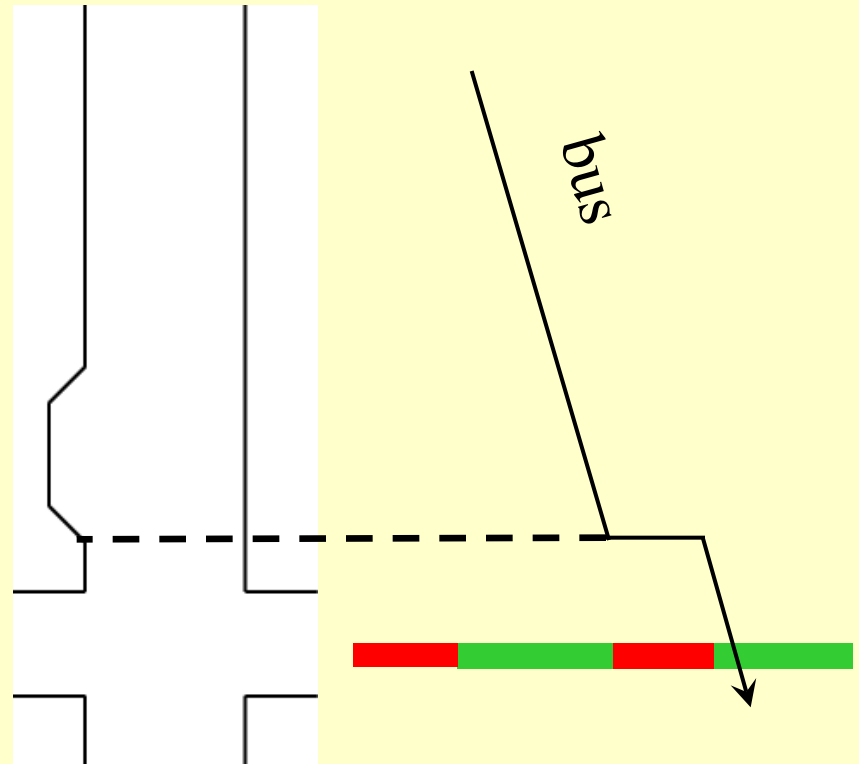


- Needs advanced detection (almost a full cycle)
- Incompatible with typical coordination logic
 - *custom programming*

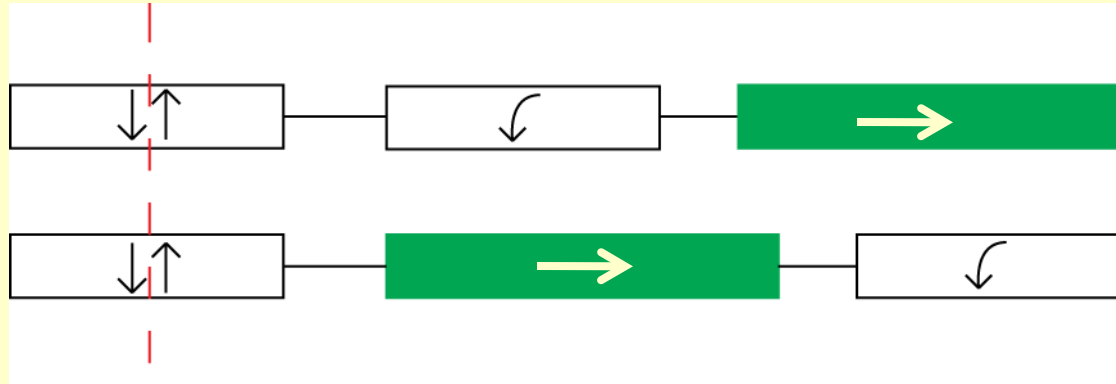
Flush-and-Return

*Early green tactic for Near-Side Stops
Tested using simulation on San Juan (PR) arterial*

- Green extension to clear queue from bus stop
- Force signal to red during stop
 - *Minimizes bus's impact on road capacity*
- Return to green as quickly as possible

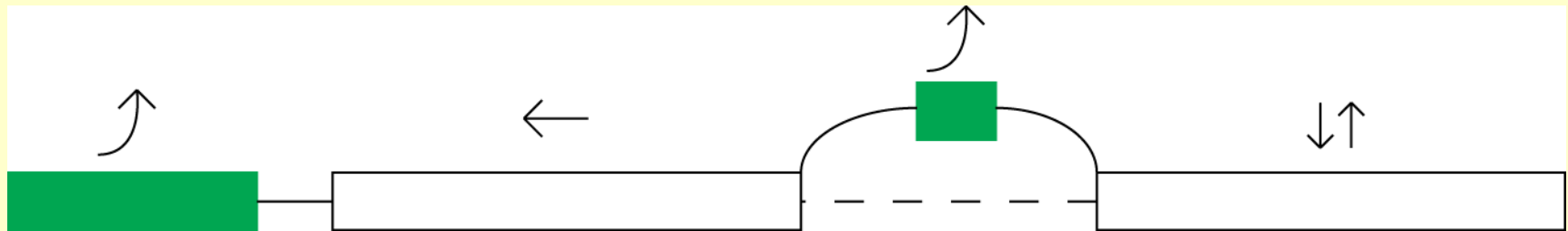


Phase Rotation

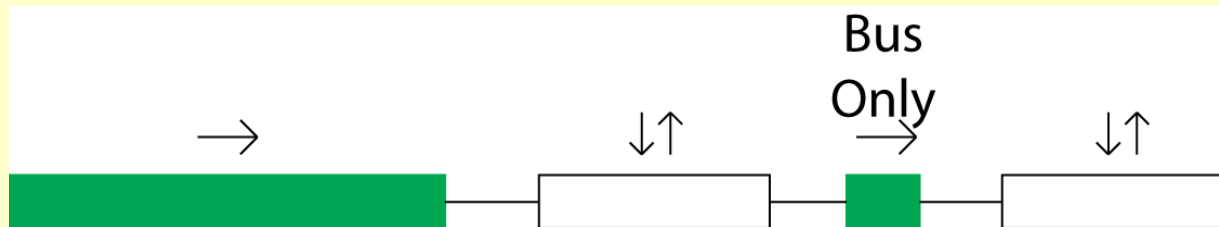


- Example: change leading bus phase to lagging
 - Lagging bus phase becomes leading – like early green
 - Leading bus phase becomes lagging – like green extension (more effective)
- Used extensively in Germany
- Zurich's pre-application safety campaign: random phase sequencing for 6 months!

Phase Insertion



- Second realization on bus detection only
 - Greatly reduces red period for bus – big reduction in delay
- Zurich’s “insert and return”



Passive Priority

Treatments that favor buses but don't rely on bus detections

- Favorable splits for bus phase
- Favorable offsets (progression) for bus
 - Hard to do over more than a few intersections due to uncertain dwell time
- Short cycles or double realizations (short red is the key)

Ruggles Bus Terminal Study

with Burak Cesme, PhD student at
Northeastern Univ.

Using VISSIM simulation and VAP signal
control programming

Main Entrance

**RUGGLES BUS
TERMINAL**

**Back
Entrance**

Exit

1

**Ruggles-
Busway**

Cass-Columbus

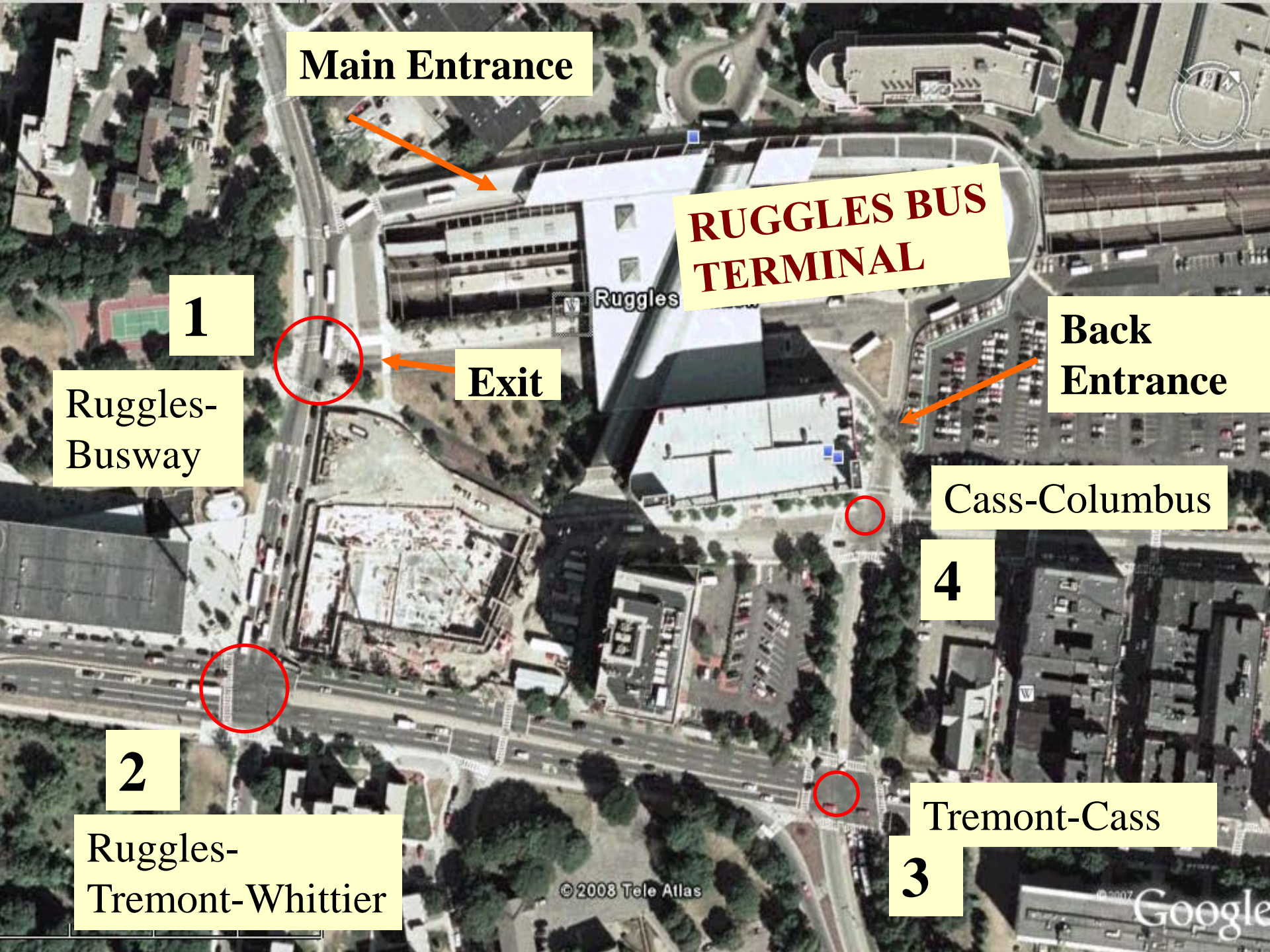
4

2

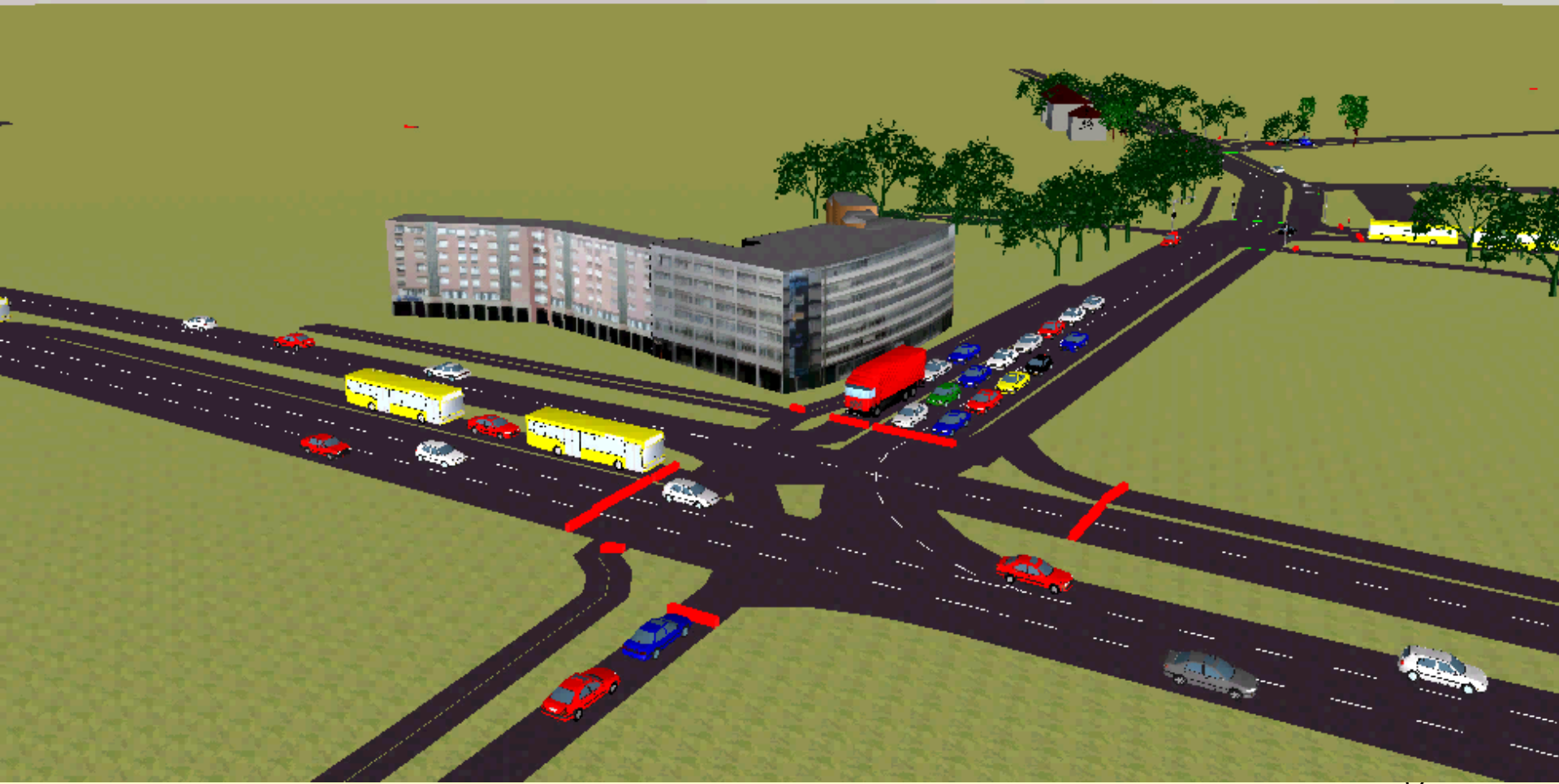
**Ruggles-
Tremont-Whittier**

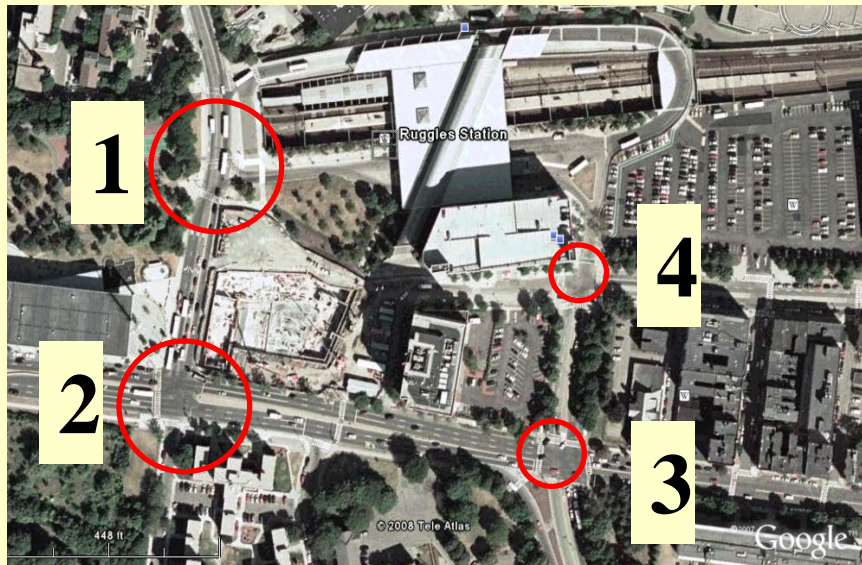
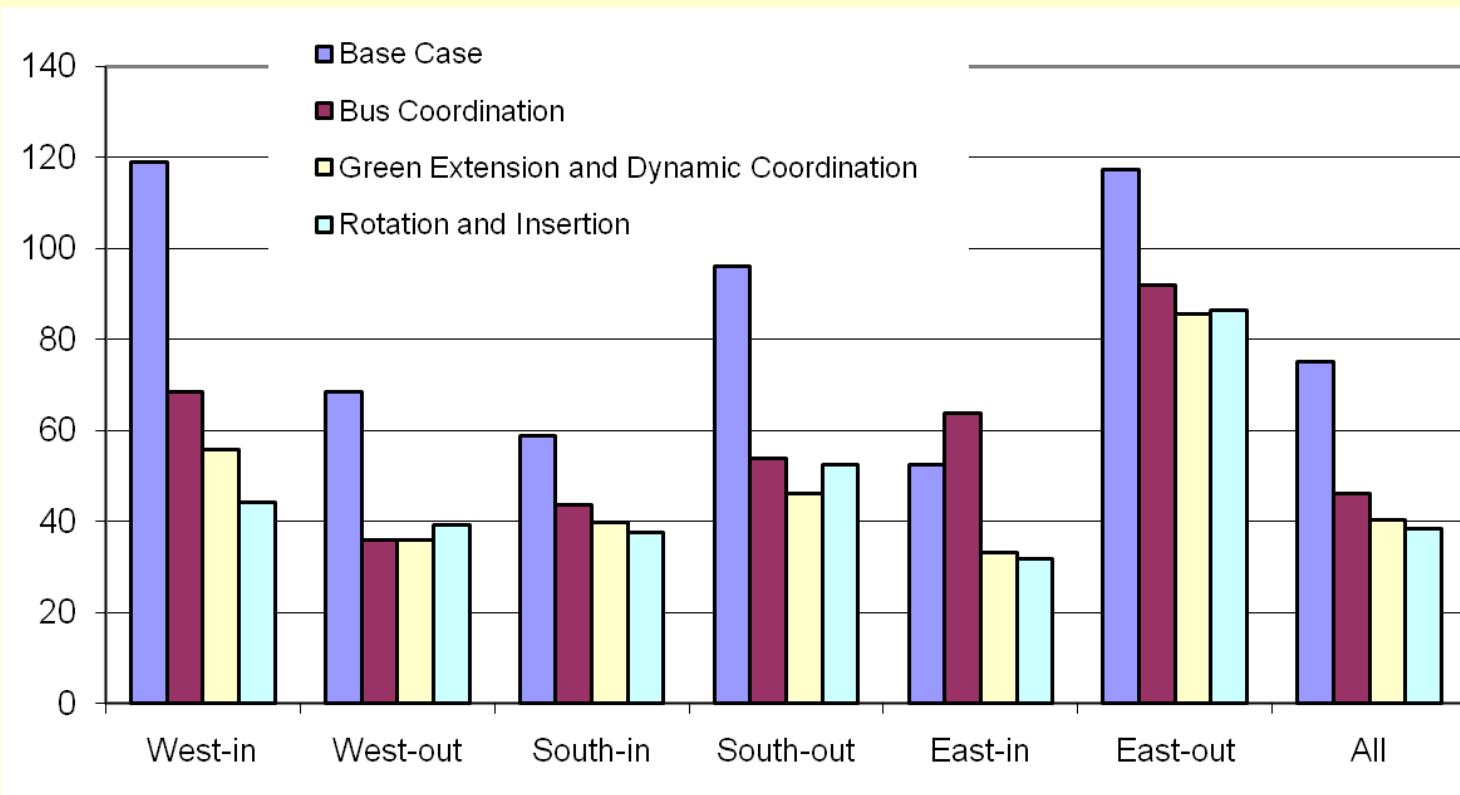
Tremont-Cass

3





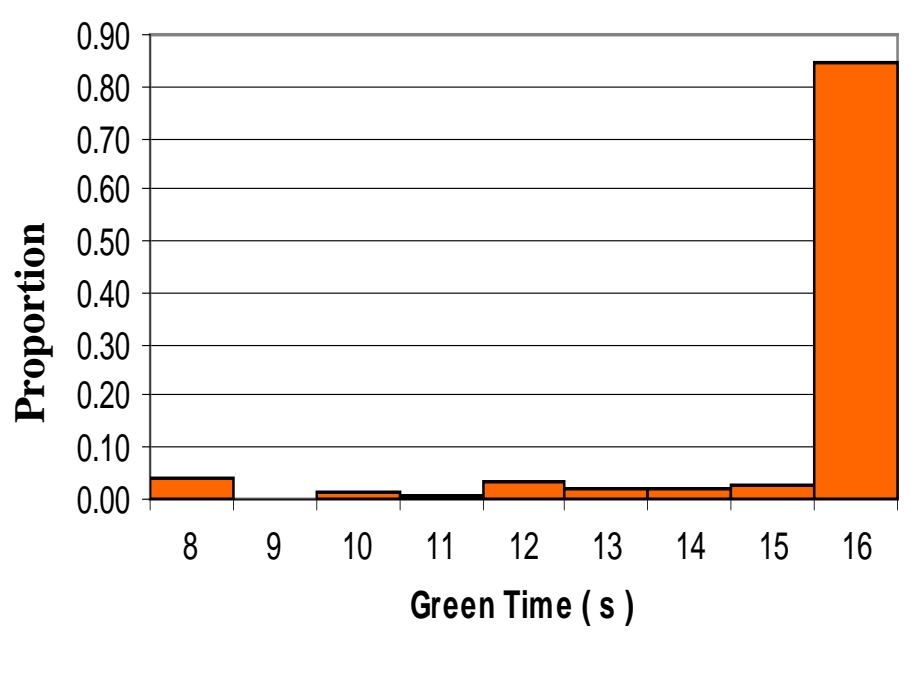




Bus Delays with Incremental Priority Treatments, by Route

Passive priority: more time to bus left turn. Note: 5 s increase in split consumes only 2.5 s!

Max Green = 16 seconds

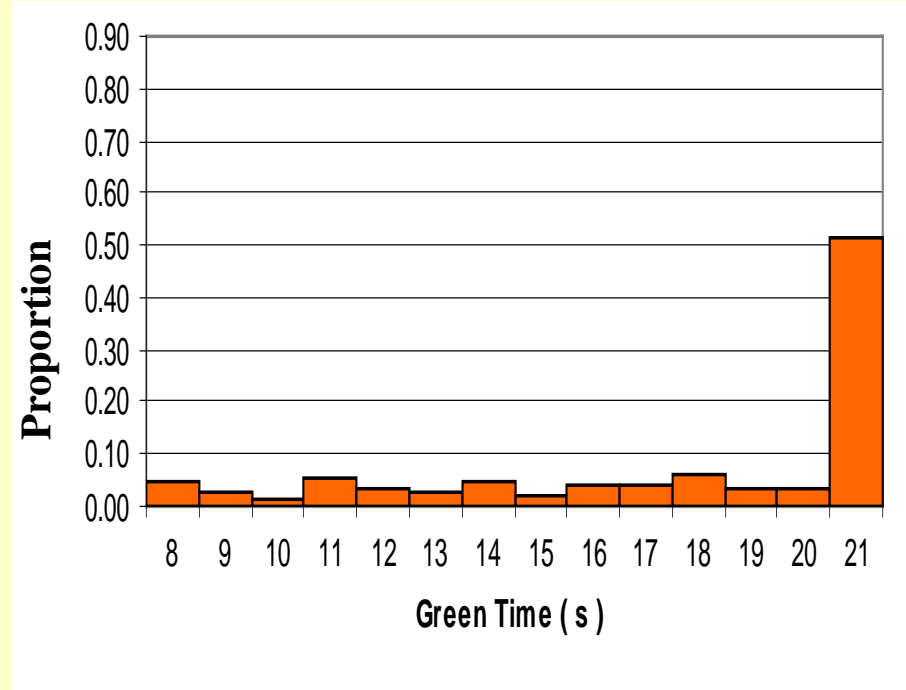


Avg Green (EBL) = 15.3s

p (max-out) = 84.6%

Avg bus delay = 98 s

Max Green = 21 seconds



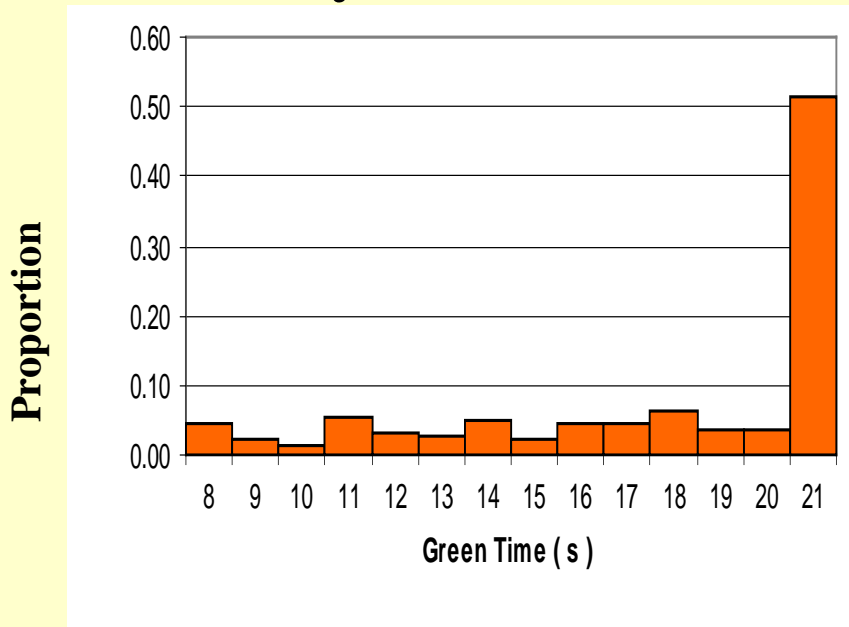
Avg Green (EBL) = 17.8s

p (max-out) = 51.2%

Avg bus delay = 67 s

Intelligent Green Extension: 10 s extension for “cost” of 0.5 s

No Priority

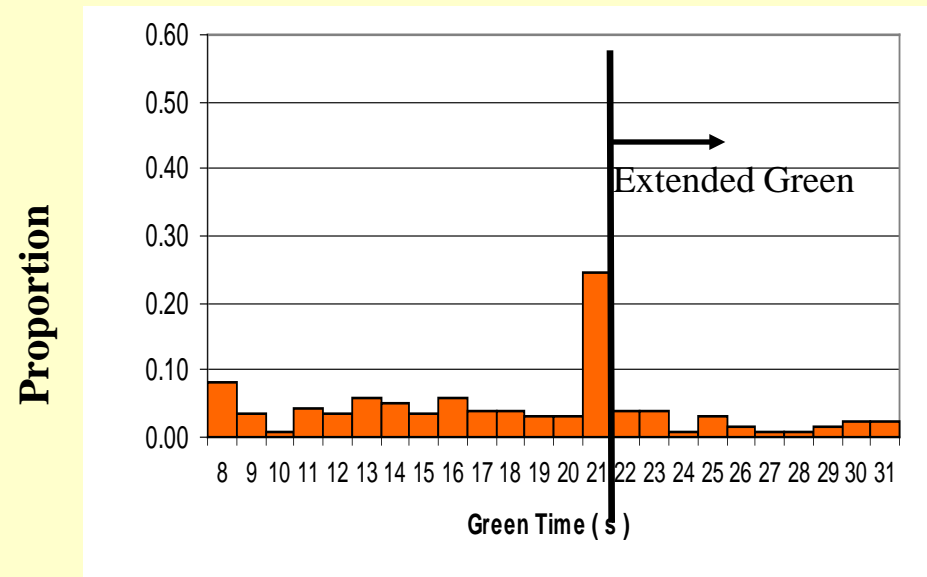


Avg Green (EBL) = 17.8s

p (max-out) = 0.512

Avg Green (WBT) =
30.3s

With Green Extension



Avg Green (EBL) = 18.1s

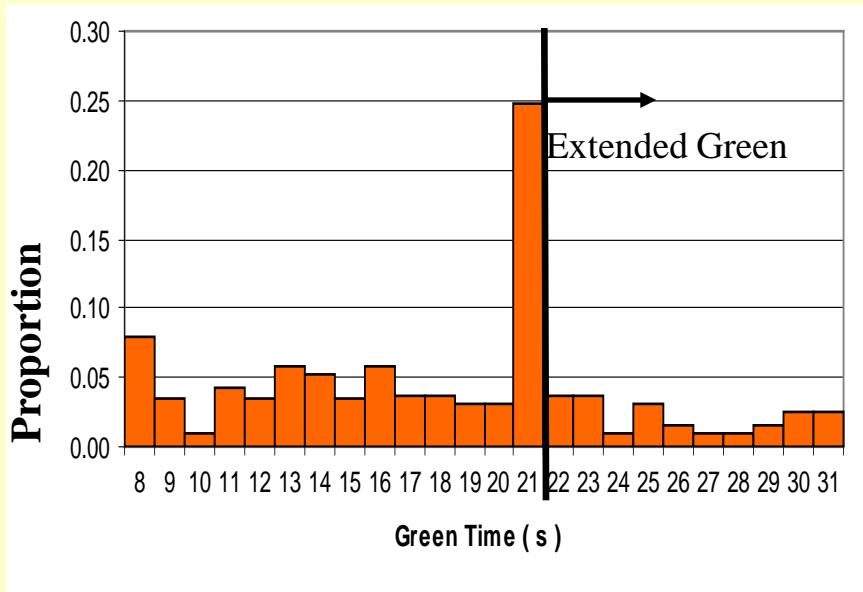
p (max-out) = 0.247

p (extended) = 0.213

Avg Green (WBT) =
29.8s

Inserting 10 s phase: only consumes 2.5 s

Green Extension Only

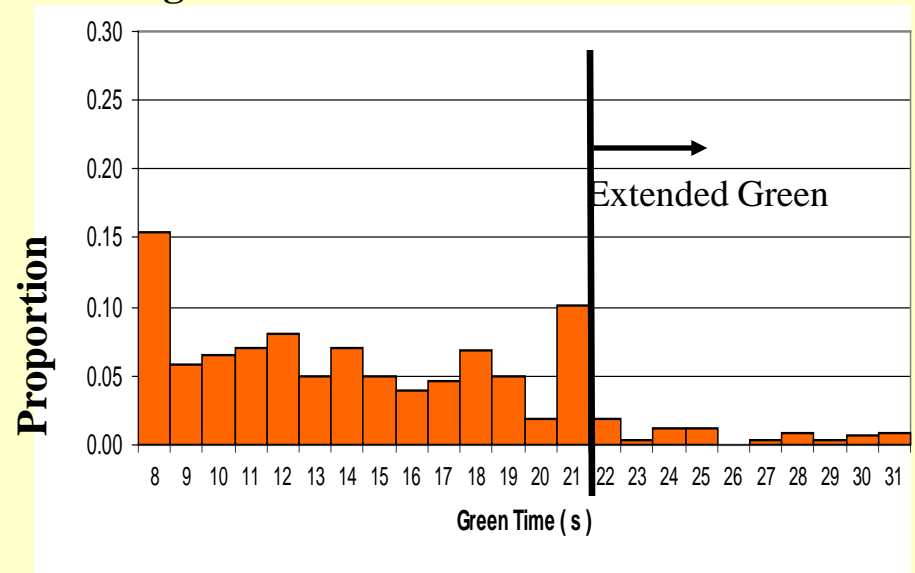


Avg Green (EBL) = 18.1s

Bus delay = 55 s

Avg Green (WBT) = 29.8s

Primary Phase , when Phase Insertion is Programmed



$p(\text{insertion}) = 0.386$
 Avg Green (primary) = 14.7s
 Avg Green (insertion) = 4.4s
 Avg Green (total) = 19.1s

Bus delay = 33 s

Avg Green (WBT) = 27.3s

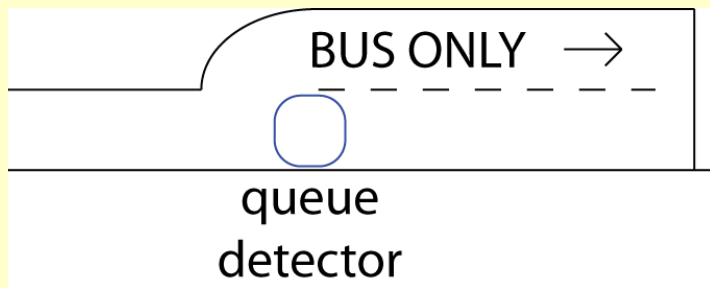
Conditional Priority

Priority to Late Buses

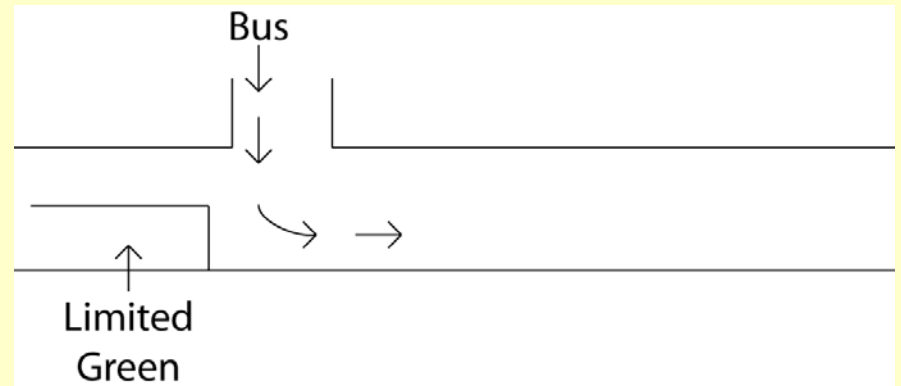
- Less interference with traffic (Eindhoven)
- Push-pull means of operational control (Eindhoven)
- What is “Late:” 15 s or 3 minutes?
- Demands fine-tuned schedule
- Headway-based priority for short-headway service

Priority Queue Management

- Detectors & logic for queue management
 - Stopped cars, not moving cars, hinder buses



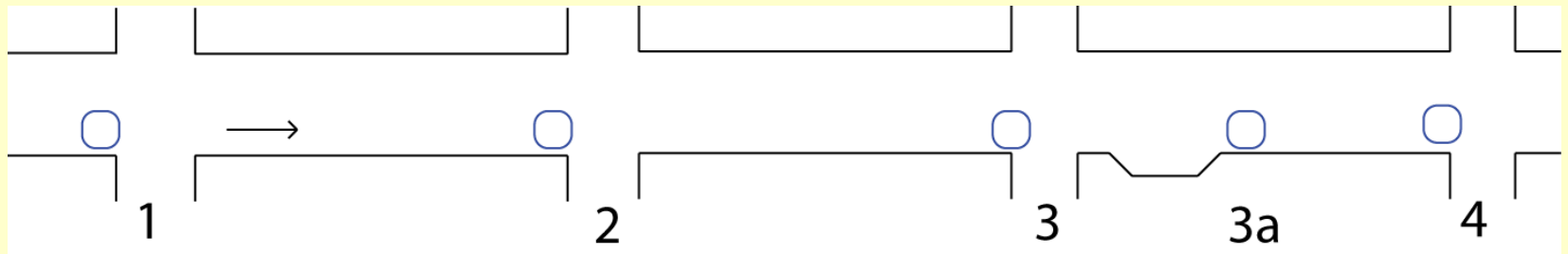
(Zurich)



(Eindhoven)

Predictive Priority

Remote, upstream detection: simulated on Huntington Ave, used in Salt Lake City



- Detector 1 used to predict bus arrival at 4 (~2 minutes advance)
- Adjust cycle lengths so that bus will arrive on green
- Last-minute priority as backup
- Adaptive (learning) algorithm for predicting bus arrival

Dynamic Coordination (Zurich)

- Small zones (1-3 intersections)
- No fixed clock
- Shape green waves through the zone around bus
- Zone boundaries are segments that offer storage buffer

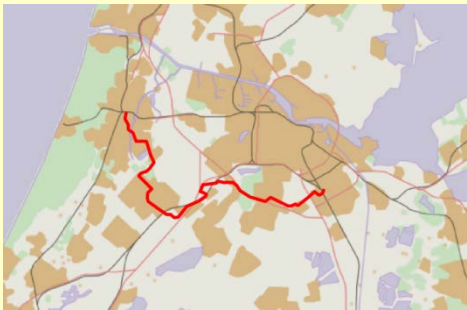
Self-Organizing Coordination

- Each signal's start of green becomes a request to downstream signal
 - Peer-to-peer communication between signals
 - upstream signal's request has lower priority than bus request
- Result: spontaneous green wave
- Inherently interruptible

Multi-Level Priority

(South Tangent = Haarlem – Airport – Amsterdam South)

- Bus is early: green extension only
- 0 to 3 min late: “normal” early green
- More than 3 min late: aggressive early green (skip competing phases)



Six Keys to Performance

1. Aim for near-zero delay
2. Multiple intelligent and aggressive tactics, with compensation
3. Coordinate with scheduling (cond'l priority)
4. Alternatives to rigid coordination
5. Advanced prediction with gradual cycle adjustments
6. Custom programming, performance measurement, & continual improvement